

3 the assumed-movement pattern includes video data showing virtual  
4 poles arranged on the outer edge of the vehicle movement area.

1 9. (Amended) The driving-operation assist according to [any one  
2 of] claim[s] 6 [to 8], characterized in that

3 the synthetic-image generating means superimposes current-position  
4 data serving as video data showing an area in which the vehicle is present, on the  
5 circumferential-state image to generate the synthetic image.

1 11. (Amended) The driving-operation assist according to [any one  
2 of] claim[s] 6 [to 10], characterized in that when actual driving operations  
3 corresponding to the above predetermined series of driving operations are started,

4 the synthetic-image generating means thereafter fixes the positional  
5 relation between the assumed-movement pattern and the circumferential-state  
6 image at the point of time when the actual driving operations are started and  
7 generates the synthetic image.

1 14. (Amended) The driving-operation assist according to [any one  
2 of] claim[s] 6 [to 13], characterized in that

3 final-position inputting means for inputting a final position which is  
4 a position of the vehicle at end of the movement and start-position determining  
5 means for obtaining a start position which is a position at start of the movement  
6 corresponding to the input final position in accordance with the assumed-  
7 movement pattern are included, and

8 the synthetic-image generating means superimposes the input final  
9 position and the start position corresponding to the input final position on the  
10 circumferential-state image to generate the synthetic image.

1 16. (Amended) The driving-operation assist according to any one of  
2 claims 1 to [15]4, characterized in that

3 assumed-movement-pattern storing means is included which holds  
4 data relating to the above predetermined series of driving operations and holds

5 assumed-movement data including at least the assumed-movement pattern.

1 18. (Amended) The driving-operation assist according to claim 16  
2 [or 17], characterized in that pattern correcting means is included which is able to  
3 update and correct the content of the assumed-movement pattern held in the  
4 assumed-movement-pattern storing means.

1 21. (Amended) The driving-operation assist according to [any one  
2 of] claim[s] 16 [to 20], characterized in that the assumed-movement data includes  
3 time-series data showing a relationship between a movement distance and a  
4 steering angle of the steering wheel of the vehicle.

1 23. (Amended) The driving-operation assist according to [any one  
2 of] claim[s] 11 [to 13 or claim 22], characterized in that operation-start detecting  
3 means is included which automatically detects that actual driving operations  
4 corresponding to the above predetermined series of driving operations are started  
5 through an input from a driver or a predetermined driving operation.

1 24. (Amended) The driving-operation assist according to [any one  
2 of] claim[s] 5 [to 23], characterized in that

3 when the viewpoint converting means changes the predetermined  
4 viewpoint, the viewpoint converting means fixes the predetermined viewpoint to  
5 the vehicle before the actual driving operations corresponding to the  
6 predetermined series of driving operations are started and changes the  
7 predetermined viewpoint to a point fixed to the three-dimensional space after the  
8 actual driving operations corresponding to the predetermined series of driving  
9 operations are started.

1 26. (Amended) The driving-operation assist according to any one of  
2 claims 1 to [5]4, characterized in that the assumed-movement pattern includes  
3 video data showing a circumscribed area on a space through which the vehicle  
4 passes when the predetermined series of driving operations are performed.

1 29. (Amended) The driving-operation assist according to any one of

MTS-3200US

2 claims 1 to [5]4, characterized in that the assumed-movement patterns respectively  
3 include a change from backward movement to forward movement or from forward  
4 movement to backward movement in the predetermined series of driving  
5 operations

1 30. (Amended) The driving-operation assist according to any one of  
2 claims 1 to [5]4, characterized in that obstacle inputting means is included which  
3 is able to input a position of an obstacle area in an image to displaying means for  
4 displaying the synthetic image from a driver.

1 33. (Amended) A recording medium characterized by storing a  
2 program of making a computer execute all of some of functions of each means of  
3 any one of claims 1 to [32]4.

A) CONT'D  
1 34. (Newly Added) The driving-operation assist according to claim  
2 12, characterized in that operation-start detecting means is included which  
3 automatically detects that actual driving operations corresponding to the above  
4 predetermined series of driving operations are started through an input from a  
5 driver or a predetermined driving operation.

1 35. (Newly Added) The driving-operation assist according to

MTS-3200US

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2 claim 13, characterized in that operation-start detecting means is included  
3 which automatically detects that actual driving operations corresponding to the  
4 above predetermined series of driving operations are started through an input  
5 from a driver or a predetermined driving operation.

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1 36. (Newly Added) The driving-operation assist according to  
2 claim 22, characterized in that operation-start detecting means is included  
3 which automatically detects that actual driving operations corresponding to the  
4 above predetermined series of driving operations are started through an input  
5 from a driver or a predetermined driving operation.

Respectfully Submitted,

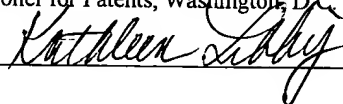
  
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